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EDITED BY MARTIN ROWE  
AND FRAN GRANVILLE

## DC-accurate, 32-bit DAC achieves 32-bit resolution

W Stephen Woodward, Chapel Hill, NC

Some applications, such as ADC testing and calibration, require a DAC with extremely good resolution, monotonicity, accuracy, and resolution. In these categories of performance, the circuit in **Figure 1** is hard to beat. Its typical specifications follow:

- Resolution = 32 bits =  $3 \times 10^{-10} = 1.2$  nV = 192 dB.
- DNL (differential nonlinearity) = 27 bits = 400 nV = 162 dB.
- INL (integral nonlinearity) = 22 bits = 1.6  $\mu$ V = 130 dB.
- Full-scale accuracy (untrimmed) = 11 bits =  $\pm 2.5$  mV = 66 dB.
- Zero accuracy = 23 bits =  $\pm 500$  nV  $\pm 10$  nV/ $^{\circ}$ C = 140 dB.
- Ripple and noise = 21 bits = 2  $\mu$ V p-p = 128 dB.

The basis of the DAC's 32-bit resolution is the summing of two 16-bit PWM signals by analog switches  $S_1$  and  $S_2$  and precision resistor network  $R_2$  through  $R_6$ . The DAC's monotonicity and DNL are theoretically infinite, and, in practice, the only limit is the  $1$ -to- $2^{16}$  ratio of  $R_2$ : ( $R_6 + R_5 + R_{S2-ON}$ ) and  $R_3$ : ( $R_6 + R_4 + R_{S2-ON}$ ). Typical accuracy of 0.1% resistors yields a DNL of approximately 0.1 ppm = 27 bits.

The less-than- $0.1\Omega$  output impedance of the AD586 reference and the 130-dB CMR (common-mode rejection) of chopper-stabilized "zero-drift" amplifier  $A_1$  mostly limit INL.  $R_7$  suppresses a potential contribution from asymmetry in  $R_{S1-ON}$ , yielding the typical INL of approximately 0.3 ppm = 22 bits.

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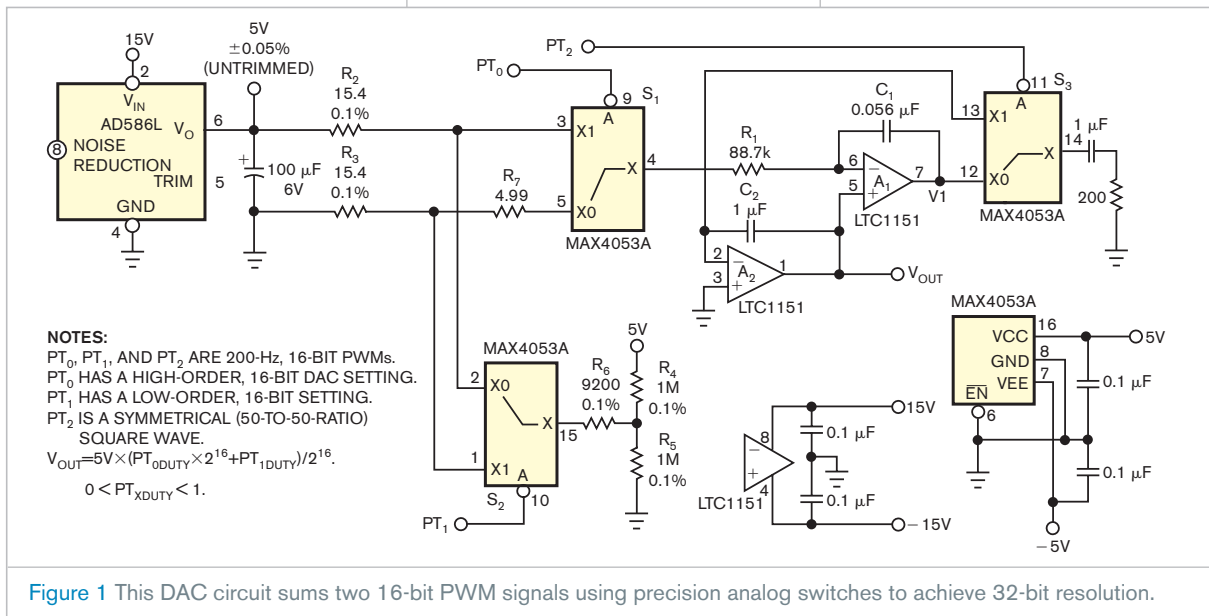
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Zero-accuracy and output-noise specs are at the low-microvolt level because of the excellent specifications



**Figure 1** This DAC circuit sums two 16-bit PWM signals using precision analog switches to achieve 32-bit resolution.

of the LTC1151  $A_1$  and  $A_2$  op amps and the charge-injection performance of the MAX4053A  $S_2$ : approximately 0.4 ppm, or 23 bits.

The precision of the AD586L 5V reference, which is  $\pm 500$  ppm untrimmed, limits absolute accuracy. If

your design requires greater accuracy, then you can use an Analog Devices (www.analog.com) simple trim circuit to further tweak it. There's nothing critical about the suggested 200-Hz PWM cycle. You need to change only  $R_1$  and  $C_1$  to accommodate any

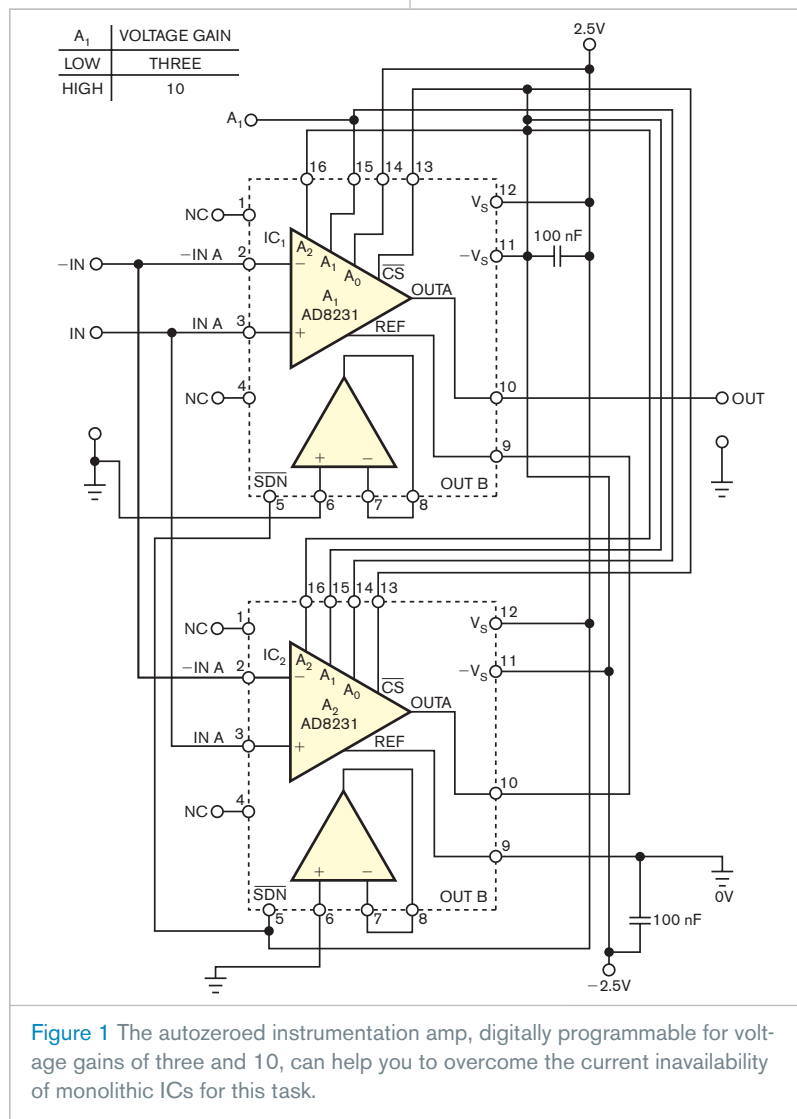
convenient frequency. How closely the  $R_1C_1$  time constant matches the PWM-cycle time determines the settling time of the  $A_1$ - $S_2$ - $A_2$  synchronous "zero-ripple" integrate-and-hold filter, and can be as fast as one cycle if the match is exact. **EDN**

## Digitally programmable instrumentation amplifier offers autozeroing

Marián Štofka, Slovak University of Technology, Bratislava, Slovakia

The current trend in advanced instrumentation amps is to use

no external resistors. In these amplifiers, a gain-control word, comprising



a binary-coded one, sets the voltage gain. Several integer gains within one to 1000 are currently available; however, this range does not yet include a gain of three. Although external-resistor-free amplifiers with a gain of three are available, they are neither instrumentation amps nor autozeroed devices (**Reference 1**). These features are essential in applications requiring accurate processing of low-level voltages. You can use the circuit in **Figure 1** for applications requiring instrumentation amps having voltage gains of three or 10 and the ability to process voltages as low as 1 mV.

This design achieves a voltage gain of three by using the "algorithm" of  $3=2+1$ . The circuit comprises two units of the Analog Devices (www.analog.com) digitally gain-programmable, autozeroed AD8231 instrumentation amp. These ICs have voltage gains that are programmable as powers of two—that is, one, two, four ... 128 (**Reference 2**). Amplifier  $A_1$  in  $IC_1$  is preset to provide a gain of two, and auxiliary amp  $A_2$  in  $IC_2$  is preset to a gain of one. The noninverting and inverting inputs of  $A_1$  and  $A_2$  connect together. The output of  $A_2$  connects with reference input  $REF_1$ , and reference input  $REF_2$  serves as a freely usable reference. You can thus calculate the output voltage as  $V_{OUT} = V_{OUT1} + V_{REF1} = V_{OUT1} + V_{OUT2} = 2\Delta V_{IN} + \Delta V_{IN} = 3\Delta V_{IN}$ , where  $\Delta V_{IN}$  is the input-difference voltage.

Similarly, you can achieve a voltage gain of 10 according to a symbolic formula of  $10=8+2$ . This time,  $A_1$  has a voltage gain of eight, and  $A_2$  has a gain of two. Using **Reference 2**, you can derive that, for gains of both three and 10,  $A_{1A1} = A_{0A2}$ . Therefore, the gain-control pins connect and remain low for a gain of three, and the high at

these pins sets the gain to 10. Note that three approaches the square root of 10, or approximately 3.16. You can therefore consider it as roughly the geometric center of a decade. **EDN**

## REFERENCES

1 Štofka, Marian, "Gain-of-three amplifier requires no external resistors," *EDN*, Aug 16, 2006, pg 74, [www.edn.com/article/CA6360318](http://www.edn.com/article/CA6360318).

2 "Zero Drift, Digitally Programmable Instrumentation Amplifier, AD8231," Analog Devices Inc, 2007, [www.analog.com/en/prod/0,2877,AD8231,00.html](http://www.analog.com/en/prod/0,2877,AD8231,00.html).

## C# application controls simple ADC

Yury Magda, Cherkassy, Ukraine

This Design Idea describes a simple and low-cost ADC that you control using the serial port of a PC running Windows XP/Vista. The hardware comprises Microchip's (www.microchip.com) 12-bit SAR (successive-approximation-register) MCP3201 ADC, which attaches to the serial port of the PC through the RTS, CTS, and DTR lines (Figure 1).

The circuit uses an SPI (serial-peripheral-interface)-compatible interface to communicate with the MCP3201. The

MAX232 chip transforms the RS-232 levels into TTL-compatible levels that the MCP3201 converter requires to operate. The analog signal comes through the IN+ pin of the MCP3201. The output digital stream of bytes on the D<sub>OUT</sub> pin goes through the CTS line to the serial port of the PC. The RTS line of the serial port provides clock pulses that go through the CLK pin of the converter. Each separate bit appears on D<sub>OUT</sub> on the falling edge of CLK, and the application should latch the bit on

the rising edge of the clock pulse.

The DTR line produces the  $\overline{CS}$  signal that frames the conversion process. The  $\overline{CS}$  signal must be low while the conversion is in progress (Figure 2).

The meaningful bits, with MSB first, appear on D<sub>OUT</sub> after the third CLK pulse

goes low. It implies that, if you miss the first three data bits, the software would programmatically realize it. The software that controls the device is written in free Microsoft (www.microsoft.com) Visual C# 2008 Express Edition. It uses a built-in SerialPort component that allows you to get full control over the serial port of the PC. You implement the software as a simple console application containing Listing 1, which is available with the Web version of this Design Idea at [www.edn.com/081030di1](http://www.edn.com/081030di1). The program is uncomplicated, so you can easily modify it. For instance, you could send the data from ADC over the Internet or pass it into Microsoft Excel or Microsoft Access for further processing.

You can improve the simplified circuit in Figure 1 for higher accuracy by placing a lowpass filter in the analog-signal chain. You should also always use a bypass capacitor with the recommended value of 1  $\mu$ F as close as possible to the device's pin. You can also replace the MCP3201 with a similar SAR ADC that works with an SPI-compatible interface. For instance, you may use an LTC1286 or an LTC1297 device from Linear Technology (www.linear.com). If you plan to use a different ADC, you must

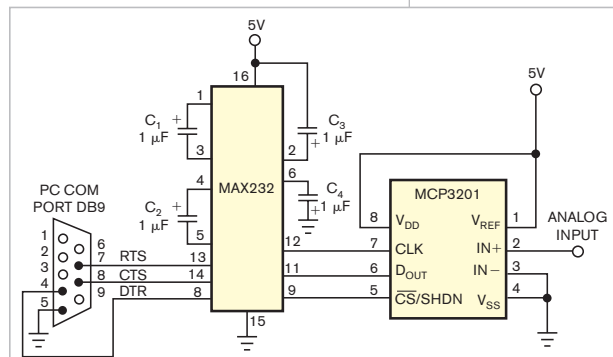


Figure 1 This simple, low-cost ADC comprises a 12-bit SAR ADC, which attaches to the serial port of the PC through the RTS, CTS, and DTR lines.

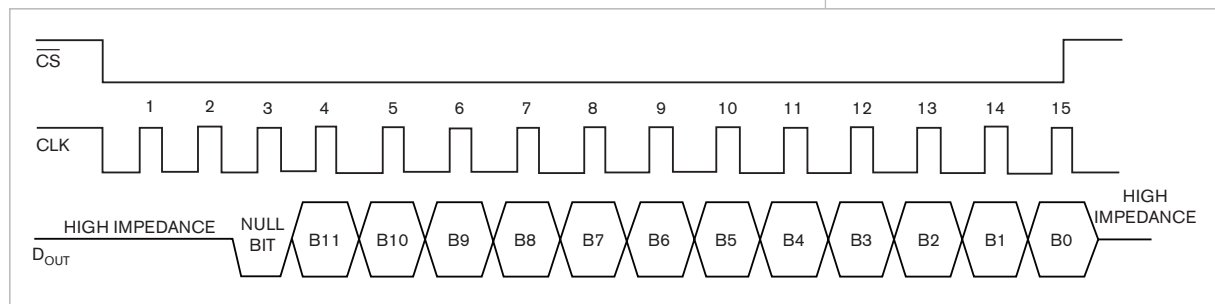



Figure 2 The DTR line produces the  $\overline{CS}$  signal that frames the conversion process. The  $\overline{CS}$  signal must be low while the conversion is in progress.

make some changes in the hardware and software. The changes necessary to the hardware are obvious, and you may need to change the software

source code of the application to correct the *for (...)* loop statement according to the timing diagram of the selected part.**EDN**

## Perform bitwise operation in Excel spreadsheets

Bruno Muswieck, Eletroeste, Uruguaiiana, Brazil

 Microsoft's (www.microsoft.com) Excel helps engineers with calculus and graphics to solve problems. But engineers often have to perform bitwise operations, too. **Figure 1** shows the bitwise operations' tables. The bitwise functions work for decimal values. If you need to use hexadecimal or binary values, you must use the Dec2Bin and Dec2Hex functions to convert all the decimal values for the desired format.

To install the add-in bitwise functions, you can download the ins.xla file from the Web version of this De-

sign Idea at [www.edn.com/081030di2](http://www.edn.com/081030di2). In Excel, go to Tools, then Add-Ins, and then Browser. Find the downloaded add-in xla file and click OK. Now, Excel can run the bitwise functions.

You can also download some examples from the *EDN* Web site at [www.edn.com/081030di2](http://www.edn.com/081030di2) (**Reference 1**).**EDN**

### REFERENCE

**1** Kagan, Aubrey, *Excel by Example: A Microsoft Excel Cookbook for Electronics Engineers*, Newnes Elsevier, 2004, ISBN 0-7506-7756-2.

AND	RESULT
0 0	0
1 0	0
0 1	0
1 1	1

OR	RESULT
0 0	0
1 0	1
0 1	1
1 1	1

XOR	RESULT
0 0	0
1 0	1
0 1	1
1 1	0

NOT	RESULT
0	255
1	254

SHIFT RIGHT		RESULT
BINARY	SHIFTED	BINARY
11010010	6	00000011

SHIFT LEFT		RESULT
BINARY	SHIFTED	BINARY
01100100	2	10010000

**Figure 1** With the help of some new add-in functions, you can perform these bitwise operations in Excel.